

3.4.2 The MCTDH Method

Generalization of the aforementioned model reductions for the finite-dimensional case to the infinite-dimensional case applicable to the multi-particle Schrödinger equation.

Approximation $\Psi \approx \mu \in \mathcal{M}$,

$$\mathcal{M} = \left\{ \mu; \mu = \sum_{j_1=1}^{N_1} \dots \sum_{j_P=1}^{N_P} a_{j_1 \dots j_P}(t) \phi_{j_1}^{(1)}(x_1, t) \dots \phi_{j_P}^{(P)}(x_P, t) \right\}$$

We impose the "Dirac-Frenkel Variational Principle" [6]

$$\langle \delta \mu | i - \frac{1}{i} H \mu \rangle = 0 \quad \forall \delta \mu \in \tilde{\mathcal{T}}_{\mu} \mathcal{M} \quad (1)$$

$\delta \mu$... "variations", i.e. tangent space to \mathcal{M} in μ .

This procedure is referred to as

"Multi-Configuration Time-Dependent Hartree Method".

For fermions (i.e., electronic Schrödinger equation),

an antisymmetrized version for indistinguishable

particles is used ("Multi-Config Time-Dep. Hartree-Fock")

$$\mathcal{M} = \left\{ \mu; \mu = \sum_{j_1=1}^N \dots \sum_{j_P=1}^N a_{j_1 \dots j_P}(t) \phi_{j_1}(x_1, t) \dots \phi_{j_P}(x_P, t) \right\}$$

$a_j = a_{j_1 \dots j_P}$ is antisymmetric under exchange of any two indices }

Formally analogous to the dynamical low rank

approximation of matrices and tensors, it is possible to derive differential equations for the coefficient tensors a_j and the "orbitals" or "single-particle functions"

$\phi_{\bar{j}k}^{(k)}$: If in addition to the variational principle (1) from p. (45) the "gaugeing" or "orthogonality constraints"

$$\langle \phi_{\bar{j}k}^{(k)} | \phi_{\bar{l}k}^{(k)} \rangle = \delta_{\bar{j}l}, \quad \forall \bar{j}, \bar{l}, k$$

$$\langle \phi_{\bar{j}k}^{(k)} | \dot{\phi}_{\bar{l}k}^{(k)} \rangle = 0$$

are imposed, the resulting equations of motion (also referred to as "working equations") are

$$i \dot{a}_j = \sum_k \langle \Phi_j | H | \Phi_k \rangle a_k \quad \forall J = (\bar{j}_1, \dots, \bar{j}_f)$$

$$i \dot{\phi}_{\bar{j}k}^{(k)} = (\text{Id} - P^{(k)}) \sum_{m_k=1}^{N_k} \sum_{l_k=1}^{N_k} [S^{(k)}]_{\bar{j}k, m_k}^{-1} \cdot \langle \Psi_{m_k}^{(k)} | H | \Psi_{l_k}^{(k)} \rangle \phi_{l_k}^{(k)}$$

where

$$\Phi_J(x_1, \dots, x_f, t) = \phi_{\bar{j}_1}^{(1)}(x_1) \dots \phi_{\bar{j}_f}^{(f)}(x_f),$$

$$\Psi_{\bar{j}k}^{(k)}(x_1, \dots, x_{k-1}, x_{k+1}, \dots, x_f, t) = \langle \phi_{\bar{j}k}^{(k)} | \mathcal{M} \rangle = \%$$

$$(\Psi_{j_k}^{(k)}) = \sum_{j_1=1}^{N_1} \dots \sum_{j_{k-1}=1}^{N_{k-1}} \sum_{j_{k+1}=1}^{N_{k+1}} \dots \sum_{j_f=1}^{N_f} a_{j_1 \dots j_f}^{(t)} \phi_{j_1}^{(1)}(x_{j_1}, t) \dots \phi_{j_{k-1}}^{(k-1)}(x_{j_{k-1}}, t) \cdot \phi_{j_{k+1}}^{(k+1)}(x_{j_{k+1}}, t) \dots \phi_{j_f}^{(f)}(x_{j_f}, t)$$

$$P^{(k)} = (P_{i_k, j_k}^{(k)})_{i_k, j_k=1}^{N_k} \text{ with } P_{i_k, j_k}^{(k)} = \langle \Psi_{i_k}^{(k)} | \Psi_{j_k}^{(k)} \rangle$$

$P^{(k)}$... orthogonal projector onto the space spanned by $\Psi_{j_k}^{(k)}$, i. e.

$$P^{(k)} \Psi = \sum_{j_k=1}^{N_k} \Psi_{j_k}^{(k)} \langle \Psi_{j_k}^{(k)} | \Psi \rangle.$$

All inner products above are meant w.r. t. all variables present in both arguments $\langle \cdot | \cdot \rangle$.

A more convenient form of the working equations may be obtained by imposing a different gauge:

Note that orthonormality $\langle \phi_i | \phi_j \rangle = \delta_{ij}$ implies $\frac{d}{dt} \langle \phi_i | \phi_j \rangle = \langle \dot{\phi}_i | \phi_j \rangle + \langle \phi_i | \dot{\phi}_j \rangle \equiv 0$.

So alternatively

$$\langle \phi_{j_k}^{(k)} | \dot{\phi}_{i_k}^{(k)} \rangle = -i \langle \phi_{j_k}^{(k)} | G^{(k)} | \phi_{i_k}^{(k)} \rangle$$

can be required, with any self-adjoint operators $G^{(k)}$,

Particularly, with the choice $G^{(k)} = T^{(k)} = -\frac{1}{2M_k} \Delta^{(k)}$,

the working equations become

$$i \dot{a}_j = \sum_k \langle \Phi_j | V | \Phi_k \rangle a_k \quad =: d_V(\phi) a(t)$$

$$i \dot{\phi}_{\hat{j}_k}^{(k)} = T^{(k)} \phi_{\hat{j}_k}^{(k)} + (\text{Id} - \rho^{(k)}) \sum_{l_k=1}^{N_k} \sum_{m_k=1}^{N_k} (\rho^{(k)})_{\hat{j}_k, m_k}^{-1} \langle \psi_{m_k}^{(k)} | V | \psi_{l_k}^{(k)} \rangle \phi_{l_k}^{(k)} \quad =: T\phi + B_V(a, \phi)$$

$$\hat{j}_k = 1, \dots, N_k, k = 1, \dots, f.$$

The method was introduced in [29] and comprehensively described in [30], where particularly the gauging topics above are treated. A more mathematical discussion is given in [31].

Quasi-Optimality of Variational Approximations

We have now introduced several variational approximations on particular manifolds \mathcal{M} , and seek to improve the very general a posteriori error bound from (32) by means of particular assumptions on the problem and on \mathcal{M} . These correspond to properties which could be indeed verified in the finite-dimensional case in the context of the low rank approximation of time-dependent matrices, see (44).

Assumptions:

- 1) $H = A + B$, A, B -- self-adjoint,
 - 2) $e^{-itA} u \in \mathcal{M} \forall u \in \mathcal{M} \Leftrightarrow Au \in \mathcal{J}_\mu \mathcal{M} \forall u \in \mathcal{M} \cap D(A)$
 - 3) $\|B\varphi\| \leq \beta \|\varphi\| \quad \forall \varphi \in \mathcal{H}$
 - 4) $\mathcal{J}_\mu \mathcal{M}$ -- complex linear, $u \in \mathcal{J}_\mu \mathcal{M} \forall u \in \mathcal{M}$
 - 5) Curvature bounds for $u, v \in \mathcal{M}, \varphi \in \mathcal{H}$

$$\|(\mathcal{P}(u) - \mathcal{P}(v))\varphi\| \leq \kappa \|u - v\| \|\varphi\|$$

$$\|\mathcal{P}^\perp(v)(u - v)\| \leq \kappa \|u - v\|^2$$
- $\mathcal{P}(u)$ -- ortho. proj. onto $\mathcal{J}_\mu \mathcal{M}, \mathcal{P}^\perp := I - \mathcal{P}$.

6) $\mathcal{P}(u(t)) \varphi \in C^1$ for $u \in C^1$, $\varphi \in \mathcal{X}$.

7) $\varphi(0) \in \mathcal{M}$, $\|\varphi(0)\| = 1$

8) $\text{dist}(\varphi(t), \mathcal{M}) \leq \frac{1}{2\kappa}$, $0 \leq t \leq t^*$

9) $\varphi, u \in \mathcal{D}(H)$,

$$\|H\varphi(t)\| \leq \mu, \|Hu(t)\| \leq \mu, \|A_M(t)\| \leq \mu.$$

10) $\text{dist}(H\varphi(t), \tilde{\mathcal{T}}_{v(t)} \mathcal{M}) \leq \delta$,

$$\text{dist}(Hu(t), \tilde{\mathcal{T}}_{u(t)} \mathcal{M}) \leq \delta,$$

$v \in \mathcal{M}$... best approximation, $\|v(t) - \varphi(t)\| = \text{dist}(\varphi(t), \mathcal{M})$.

Remark: The critical assumption 3) is not satisfied for the Coulomb potential. For the necessary modifications, see [13].

Under the assumptions 1) - 10) above, we can prove the following Theorem:

Theorem (Quasi-optimality of variational approx.):

Under the assumptions 1) - 10), the error satisfies

$$\|u(t) - \varphi(t)\| \leq d(t) + C \cdot e^{\gamma t} \int_0^t d(s) ds, \quad 0 \leq t \leq t^*,$$

$$d(t) := \text{dist}(\varphi(t), \mathcal{M}), \quad \gamma = 2\kappa\delta, \quad C = \beta + 3\kappa\mu.$$

Proof:

a) v is characterized by

$$P(v)(v - \varphi) = 0, \tag{*}$$

$$\Rightarrow P(v)(\dot{v} - \dot{\varphi}) + [P'(v) \cdot (v - \varphi)] \dot{v}$$

(note: $[P'(v) \cdot \varphi] \dot{v} = \frac{d}{dt} P(v(t)) \varphi$)

$$\dot{v} \in T_v M \Rightarrow P(v) \dot{v} = \dot{v} \rightsquigarrow$$

$$(I + P'(v) \cdot (v - \varphi)) \dot{v} = P(v) \dot{\varphi}. \tag{1}$$

By 5) and 8) we thus have

$$\|P'(v) \cdot (v - \varphi)\| \leq \alpha \|v - \varphi\| \leq \frac{1}{2}$$

$\Rightarrow I + P'$ in (1) is invertible, and

$$\dot{v} = P(v) \dot{\varphi} + r(v, \varphi), \quad \|r(v, \varphi)\| \leq 2\alpha \mu \|v - \varphi\|,$$

using 9), $\|\dot{\varphi}\| = \|H\varphi\| \leq \mu$.

Recall that $\dot{u} = P(u) \frac{1}{\epsilon} H u$.

In the following, assume $v(\epsilon) \in D(H) = D(A)$.

(This is an assumption on the regularity of the best approximation!)

b) $\dot{u} - \dot{v} = \mathcal{P}(u) \frac{1}{i} H u - \mathcal{P}(v) \dot{\psi} - g(v, \psi) \quad | \cdot (u-v)$

$\langle u-v | \dot{u} - \dot{v} \rangle = \langle u-v | \mathcal{P}(u) \frac{1}{i} H u - \mathcal{P}(v) \dot{\psi} - g(v, \psi) \rangle$

$\text{Re} \langle u-v | \dot{u} - \dot{v} \rangle = \text{Re} \langle u-v | \mathcal{P}(u) \frac{1}{i} H u - \mathcal{P}(v) \dot{\psi} - g(v, \psi) \rangle = (*)$

$\frac{1}{2} \frac{d}{ds} \|u-v\|^2 = \|u-v\| \frac{d}{ds} \|u-v\|$

$(*) = \text{I} + \text{II} + \text{III}$

$\text{I} = -\text{Re} \langle u-v | \mathcal{P}(u) i H u - \mathcal{P}(v) i H v \rangle$

$\text{II} = -\text{Re} \langle u-v | \mathcal{P}(v) i H (v - \psi) \rangle$

$\text{III} = -\text{Re} \langle u-v | r(v, \psi) \rangle$

c) $A_M \in \mathcal{T}_M M \Rightarrow \mathcal{P}^\perp(v) i A v = 0, H = A + B \text{ selfadjoint} \Rightarrow$

$\text{I} = \text{Re} \langle u-v | \mathcal{P}^\perp(u) i H u - \mathcal{P}^\perp(v) i H v \rangle$

(since $\text{Re} \langle u-v | i H u - i H v \rangle = \text{Re} (i \underbrace{\langle u-v | H | u-v \rangle}_{\in \mathbb{R}})$
 $= 0$)

$= \text{Re} \langle u-v | \mathcal{P}^\perp(u) i H u \rangle - \text{Re} \langle u-v | \mathcal{P}^\perp(v) i B v \rangle.$

$\text{II} = -\text{Re} \langle u-v | \mathcal{P}(v) i A (v - \psi) \rangle - \text{Re} \langle u-v | \mathcal{P}(v) i B (v - \psi) \rangle.$

Using Assumption 4) $\Rightarrow \mathcal{P}(v)v = v.$

(*) on p. 51 implies thus

$v = \mathcal{P}(v)\psi, v - \psi = \mathcal{P}^\perp(v)(v - \psi) = -\mathcal{P}^\perp(v)\psi.$

$$\langle v | P(v) : A(v - \psi) \rangle = - \langle v | P(v) : A P^\perp(v) \psi \rangle =$$

$$= \langle P^\perp(v) : A v | \psi \rangle = 0$$

(by Assumption 2)

Similarly,

$$\langle u | : A P^\perp(u) (v - \psi) \rangle = 0.$$

Together, we have

$$\langle u - v | P(v) : A(v - \psi) \rangle =$$

$$= \langle u | : A(v - \psi) \rangle - \langle u - v | P^\perp(v) : A(v - \psi) \rangle$$

$$= - \langle u | : A (P^\perp(u) - P^\perp(v)) (v - \psi) \rangle +$$

$$+ \langle u - v | P^\perp(v) : A \psi \rangle =$$

$$= - \langle i A u | (P(u) - P(v)) (v - \psi) \rangle +$$

$$+ \langle P^\perp(v) (u - v) | P^\perp(v) : H \psi \rangle -$$

$$- \langle u - v | P^\perp(v) : B \psi \rangle.$$

Thus,

$$I + II = \operatorname{Re} \langle P^\perp(u) (u - v) | P^\perp(u) : H u \rangle -$$

$$- \operatorname{Re} \langle u - v | : B (v - \psi) \rangle +$$

$$+ \operatorname{Re} \langle i A u | (P(u) - P(v)) (v - \psi) \rangle -$$

$$- \operatorname{Re} \langle P^\perp(v) (u - v) | P^\perp(v) : H \psi \rangle.$$

With the assumptions,

$$\begin{aligned}
|I+II| &\leq \alpha \|u-v\|^2 \delta + \|u-v\| \cdot \beta \|v-\varphi\| + \\
&\quad + \mu \alpha \|u-v\| \|v-\varphi\| + \alpha \|u-v\|^2 \delta = \\
&= 2\alpha \delta \|u-v\|^2 + (\beta + \alpha\mu) \|u-v\| \|v-\varphi\|.
\end{aligned}$$

$$\Rightarrow \frac{d}{dt} \|u-v\| \leq \gamma \|u-v\| + C \|v-\varphi\|,$$

$$\gamma := 2\alpha\delta, \quad C := \beta + 3\alpha\mu.$$

Grönwall lemma \Rightarrow

$$\|u(t) - v(t)\| \leq C \cdot e^{\gamma t} \int_0^t \|v(s) - \varphi(s)\| ds$$

Triangle inequality for $u - \varphi = (u - v) + (v - \varphi)$

yields the proposition of the Theorem. //